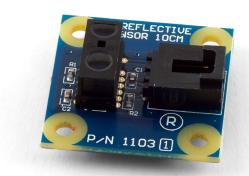


# **Product Manual**

1103 - IR Reflective Sensor 10cm



Phidgets 1103 - Product Manual For Board Revision 1 © Phidgets Inc. 2009

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## **Product Features**

- Can detect the presence of an object at a distance of 0 to 10cm
- Works just as well in both dim and well lit areas
- Does not depend on the reflective property of the object

#### **Connections**

Designed to connect to a:

- 1018 PhidgetInterfaceKit 8/8/8
- 1019 PhidgetInterfaceKit 8/8/8 w/6 Port Hub
- 1070 PhidgetSBC
- 1202 PhidgetTextLCD

## **Type of Measurement**

The sensor uses ratiometric measurement.

#### **Checking the Contents**

#### You should have received:

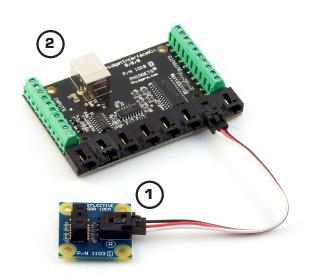
- An IR Reflective Sensor 10cm
- A Sensor Cable

# In order to test your new Phidget you will also need:

- A Phidget InterfaceKit 8/8/8 or a PhidgetTextLCD
- A USB Cable

#### Connecting all the pieces

- 1. Connect the IR Reflective Sensor 10cm to the Analog Input 6 on the PhidgetInterfaceKit 8/8/8 board using the sensor cable.
- 2. Connect the PhidgetInterfaceKit to your PC using the USB cable.



#### **Testing Using Windows 2000/XP/Vista**

#### **Downloading the Phidgets drivers**

Make sure that you have the current version of the Phidget library installed on your PC. If you don't, do the following:

Go to www.phidgets.com >> Drivers

Download and run Phidget21 Installer (32-bit, or 64-bit, depending on your PC)

You should see the tion on the right hand corner of the Task Bar.

#### **Running Phidgets Sample Program**

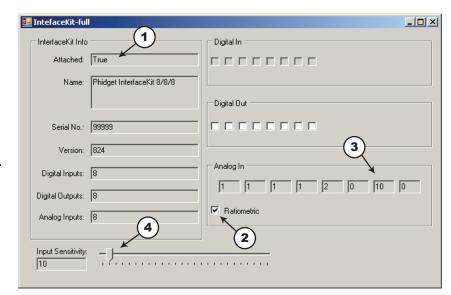
Double clicking on the icon loads the Phidget Control Panel; we will use this program to make sure that your new Phidget works properly. Since the sensor is connected to a 1018, the computer will see only the 1018. The sensor is providing data through the Analog input it is connected to.

The source code for the InterfaceKit-full sample program can be found under C# by clicking on www.phidgets.com >> Programming.

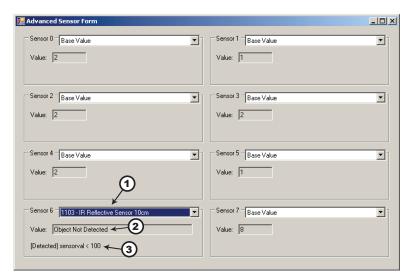
Double Click on the Phidget Control Panel and make sure that the Phidget InterfaceKit 8/8/8 is properly attached to your PC.



- Double Click on **Phidget** InterfaceKit 8/8/8 in the Phidget Control Panel to bring up InterfaceKit-full and check that the box labelled Attached contains the word True.
- 2. Make sure that the Ratiometric box is Ticked.
- 3. Move an object in front of the sensor. The sensor value changes from 1000 to 0 as the object is moving closer to the sensor from a distance of 10cm. When the object is more than 10cm away, the value goes back to 1000.
- 4. You can adjust the input sensitivity by moving the slider pointer.
- 5. Click on the Sensors button to bring up the Advanced Sensor Form.



- 1. In the Sensor 6 box, select the 1103 IR Reflective Sensor 10cm from the drop down menu.
- 2. Shows detection of the object as it gets closed than 10cm from the 1103.
- 3. Formula used to convert the analog input SensorValue into detection/non-detection.



#### **Testing Using Mac OS X**

- Click on System Preferences >> Phidgets (under Other) to activate the Preference Pane
- Make sure that the Phidget InterfaceKit 8/8/8 is properly attached.
- Double Click on Phidget InterfaceKit 8/8/8 in the Phidget Preference Pane to bring up the InterfaceKit-Full example. This example will function in a similar way as the Windows version, but note that it does not include an Advanced Sensor Display.

### **Programming a Phidget**

Phidgets' philosophy is that you do not have to be an electrical engineer in order to do projects that use devices like sensors, motors, motor controllers, and interface boards. All you need to know is how to program. We have developed a complete set of Application Programming Interfaces (API) that are supported for Windows, Mac OS X, and Linux. When it comes to languages, we support VB6, VB.NET, C#.NET, C, C++, Flash 9, Flex, Java, LabVIEW, Python, Max/MSP, and Cocoa.

#### **Code Samples**

We have written sample programs to illustrate how the APIs are used.

Due to the large number of languages and devices we support, we cannot provide examples in every language for every Phidget. Some of the examples are very minimal, and other examples will have a full-featured GUI allowing all the functionality of the device to be explored. Most developers start by modifying existing examples until they have an understanding of the architecture.

Go to www.phidgets.com >> Programming to see if there are code samples written for your device. Find the language you want to use and click on the magnifying glass besides "Code Sample". You will get a list of all the devices for which we wrote code samples in that language.

If this is your first time writing a program to control a Phidget, you should read the Getting Started Guide for the language you are planning to use.

#### **Coding for your Sensor**

Phidget analog sensors do not have their own API, but instead their output is a voltage that is converted to a digital value and accessed through the SensorValue properties and events on a PhidgetInterfaceKit. It is not possible to programmatically identify which sensor is attached to the Analog Input. Your application will need to apply any formulas from this manual to the SensorValue to translate it into usable data.

See the PhidgetInterfaceKit product manual for an overview of its API and a description of our architecture.

#### **Technical Information**

This sensor can detect the presence of an object at 10cm. This sensor does not rely on the reflective properties of the surface of the object. The sensor cannot detect the presence of the object if it is emitting large amounts of light, such as a light bulb.

The sensor will not detect objects that are more than 10cm away, but will detect objects that are closer than 10cm. When an object is in the line of sight of the sensor at a distance of 10cm or closer, the sensor value will decrease from 1000 to 0. Once the object leaves the line of sight, the value is restored to 1000.

The IR sensor works just as well in both dim and well lit areas.

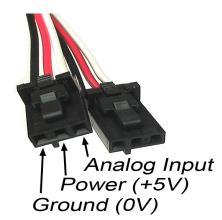
#### **Other Interfacing Alternatives**

If you want maximum accuracy, you can use the RawSensorValue property from the PhidgetInterfaceKit. To adjust a formula, substitute (SensorValue) with (RawSensorValue / 4.095)

If the sensor is being interfaced to your own Analog to Digital Converter and not a Phidget device, our formulas can be modified by replacing (SensorValue) with (Vin \* 200). It is important to consider the voltage reference and input voltage range of your ADC for full accuracy and range.

#### **Analog Input Cable Connectors**

Each Analog Input uses a 3-pin, 0.100 inch pitch locking connector. Pictured here is a plug with the connections labeled. The connectors are commonly available - refer to the Table below for manufacturer part numbers.

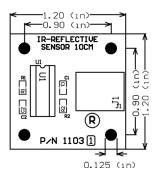


Cable Connectors			
Manufacturer	Part Number	Description	
Molex	50-57-9403	3 Position Cable Connector	
Molex	16-02-0102	Wire Crimp Insert for Cable Connector	
Molex	70543-0002	3 Position Vertical PCB Connector	
Molex	70553-0002	3 Position Right-Angle PCB Connector (Gold)	
Molex	70553-0037	3 Position Right-Angle PCB Connector (Tin)	
Molex	15-91-2035	3 Position Right-Angle PCB Connector - Surface Mount	

Note: Most of the above components can be bought at www.digikey.com

## **Mechanical Drawing**

1:1 scale



**Device Specifications** 

Characteristic	Value
Current Consumption	9mA
Output Impedance	1K ohms
USB Supply Voltage	4.75VDC to 5.25VDC

**Product History** 

Date	<b>Board Revision</b>	Comment
March 2006	0	Product Release
April 2010	1	New Sensor Chip mounted vertically on board (sensor faces up)

## **Support**

Call the support desk at 1.403.282.7335 8:00 AM to 5:00 PM Mountain Time (US & Canada) - GMT-07:00 or

E-mail us at: support@phidgets.com